

X-LSM050B-E03 Datasheet



- 25, 50, 100, 150, 200 mm travel
- Up to 104 mm/s speed and up to 55 N thrust
- Recirculating ball bearing design for high load (25 kg) and long lifetime
- Built-in controller; daisy-chains with other Zaber products
- Integrated, 200 CPR, motor mounted encoder provides slip/stall detection and recovery
- Custom versions available

X-LSM-E Series Overview

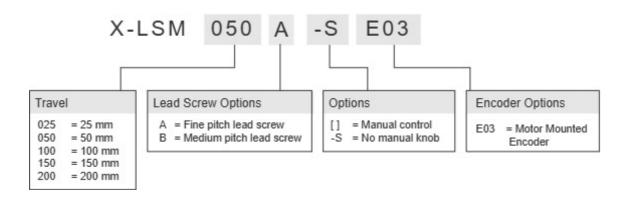
Zaber's X-LSM-E Series devices are computer-controlled, motorized linear stages with high thrust and speed capabilities and a compact size. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

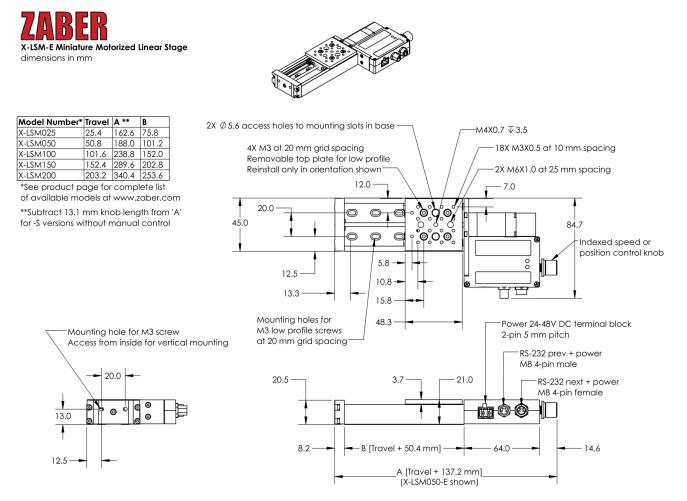
At only 21 mm high, these miniature stages are excellent for applications where a small profile is required. The X-LSM-E's innovative design allows speeds up to 104 mm/s and loads up to 25 kg. Like all of Zaber's products, the X-LSM-E Series is designed to be 'plug and play' and very easy to set up and operate. If you are considering a multi-axis system, in the XY configuration, these stages make excellent microscope stages. Adding an X-JOY3 joystick controller allows manual control of both X and Y or XYZ axes from a single interface as well as allowing microscope stage positions to be saved and recalled at the touch of a button.

For more information visit: https://www.zaber.comproducts/linear-stages/X-LSM-E

X-LSM-E Series Part Numbering



X-LSM050B-E03 Drawings

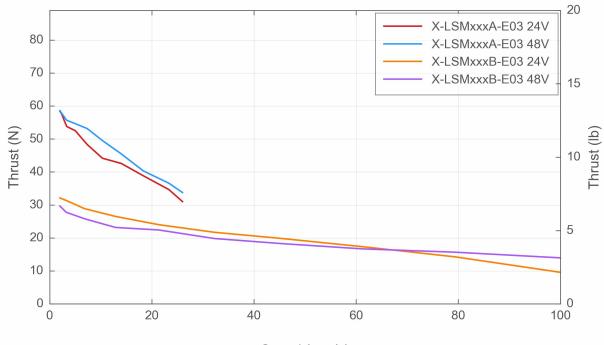


DWG 3429 R0

X-LSM050B-E03 Specifications

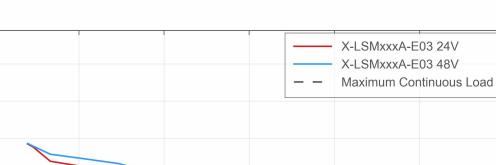
Specification	Value	Alternate Unit
Microstep Size (Default Resolution)	0.1905 µm	
Built-in Controller	Yes	
Travel Range	50.8 mm	2.000"
Accuracy (unidirectional)	25 µm	0.000984"
Repeatability	< 6 µm	< 0.000236"
Backlash	< 16 µm	< 0.000630"
Maximum Speed	104 mm/s	4.094"/s
Minimum Speed	0.000116 mm/s	0.000005"/s
Speed Resolution	0.000116 mm/s	0.000005"/s
Encoder Resolution	200 CPR	800 states/rev
Encoder Type	Rotary quadrature encoder	
Peak Thrust	25 N	5.6 lb
Maximum Continuous Thrust	25 N	5.6 lb
Communication Interface	RS-232	
Communication Protocol	Zaber ASCII (Default), Zaber Binary	
Data Cable Connection	Locking 4-pin M8	
Maximum Centered Load	250 N	56.1 lb
Maximum Cantilever Load	10 N-m	7.4 ft-lb
Guide Type	Recirculating ball bearing	
Vertical Runout	< 11 µm	< 0.000433"
Horizontal Runout	< 14 µm	< 0.000551"
Pitch	0.03°	0.523 mrad
Roll	0.03°	0.523 mrad
Yaw	0.03°	0.523 mrad
Stiffness in Pitch	150 N-m/°	116 µrad/N-m
Stiffness in Roll	150 N-m/°	116 µrad/N-m
Stiffness in Yaw	150 N-m/°	116 µrad/N-m
Power Supply	24-48 VDC	
Dower Dlug	Quin Quan Transient	
Power Plug	2-pin Screw Terminal	

Specification	Value	Alternate Unit
Linear Motion Per Motor Rev	2.4384 mm	0.096"
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	600 mA/phase	
Inductance	3.5 mH/phase	
Default Resolution	1/64 of a step	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic hall sensor	
Manual Control	Yes	
Axes of Motion	1	
LED Indicators	Yes	
Mounting Interface	M3 and M6 threaded holes and M4 threaded centre hole	
Stage Parallelism	< 25 µm	< 0.000984"
Operating Temperature Range	0 to 50 °C	
RoHS Compliant	Yes	
CE Compliant	Yes	
Vacuum Compatible	No	
Weight	0.36 kg	0.794 lb

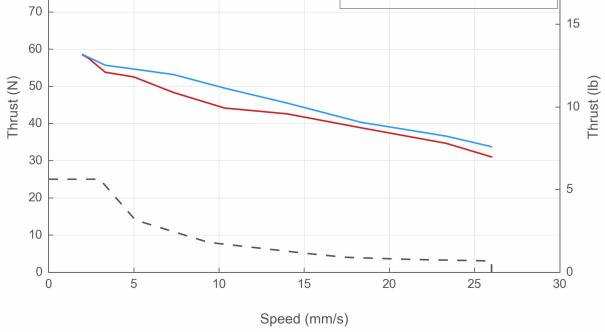


Thrust Speed Performance

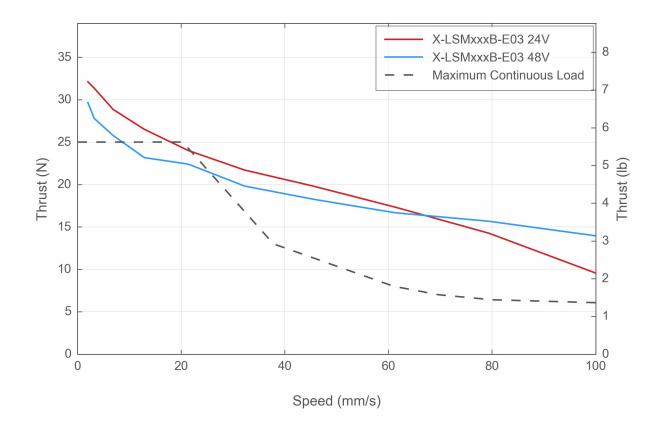
Speed (mm/s)



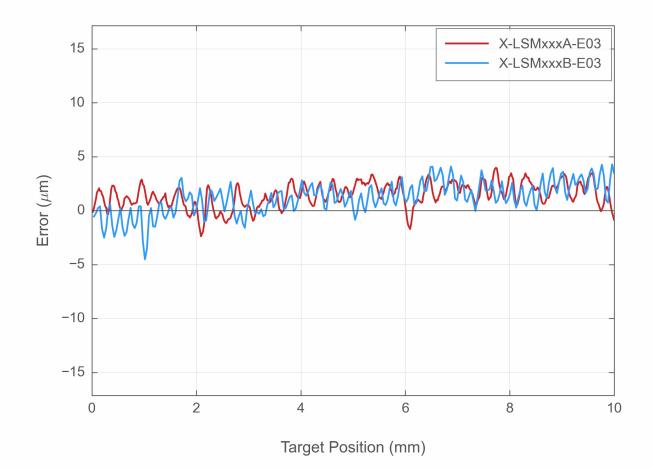
Thrust Speed Performance

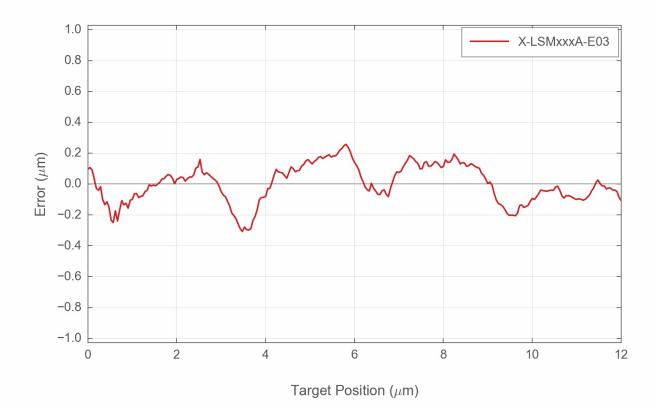






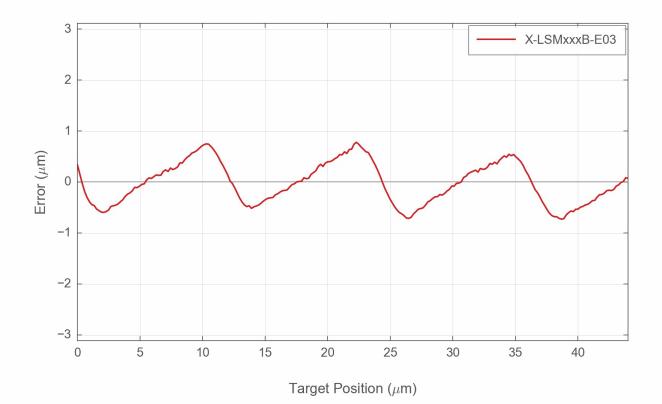
Typical Accuracy



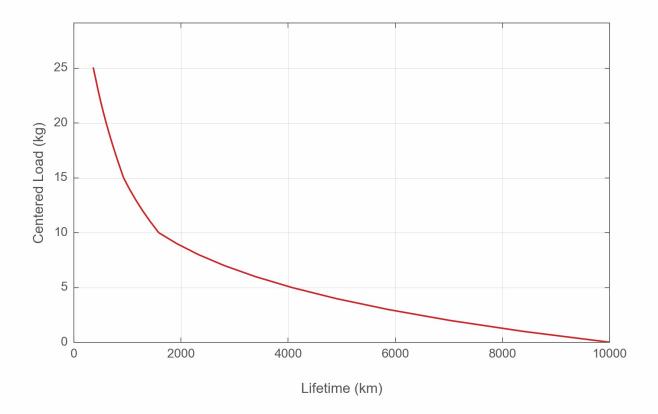


Typical Microstepping Accuracy

Typical Microstepping Accuracy



LSM Linear Bearing Lifetime



Contact

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