

# X-LSM100A-SE03 Datasheet



- 25, 50, 100, 150, 200 mm travel
- Up to 104 mm/s speed and up to 55 N thrust
- Recirculating ball bearing design for high load (25 kg) and long lifetime
- Built-in controller; daisy-chains with other Zaber products
- Integrated, 200 CPR, motor mounted encoder provides slip/stall detection and recovery
- Custom versions available

### X-LSM-E Series Overview

Zaber's X-LSM-E Series devices are computer-controlled, motorized linear stages with high thrust and speed capabilities and a compact size. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

At only 21 mm high, these miniature stages are excellent for applications where a small profile is required. The X-LSM-E's innovative design allows speeds up to 104 mm/s and loads up to 25 kg. Like all of Zaber's products, the X-LSM-E Series is designed to be 'plug and play' and very easy to set up and operate. If you are considering a multi-axis system, in the XY configuration, these stages make excellent microscope stages. Adding an X-JOY3 joystick controller allows manual control of both X and Y or XYZ axes from a single interface as well as allowing microscope stage positions to be saved and recalled at the touch of a button.

For more information visit: https://www.zaber.comproducts/linear-stages/X-LSM-E

#### X-LSM-E Series Part Numbering



# X-LSM100A-SE03 Drawings



DWG 3429 R0

# X-LSM100A-SE03 Specifications

Specification	Value	Alternate Unit
Microstep Size (Default Resolution)	0.047625 μm	
Built-in Controller	Yes	
Travel Range	101.6 mm	4.000"
Accuracy (unidirectional)	35 µm	0.001378"
Repeatability	< 3 µm	< 0.000118"
Backlash	< 12 µm	< 0.000472"
Maximum Speed	26 mm/s	1.024"/s
Minimum Speed	0.000029 mm/s	0.000001"/s
Speed Resolution	0.000029 mm/s	0.000001"/s
Encoder Resolution	200 CPR	800 states/rev
Encoder Type	Rotary quadrature encoder	
Peak Thrust	55 N	12.3 lb
Maximum Continuous Thrust	25 N	5.6 lb
Communication Interface	RS-232	
Communication Protocol	Zaber ASCII (Default), Zaber Binary	
Data Cable Connection	Locking 4-pin M8	
Maximum Centered Load	250 N	56.1 lb
Maximum Cantilever Load	10 N-m	7.4 ft-lb
Guide Type	Recirculating ball bearing	
Vertical Runout	< 18 µm	< 0.000709"
Horizontal Runout	< 18 µm	< 0.000709"
Pitch	0.04°	0.698 mrad
Roll	0.04°	0.698 mrad
Yaw	0.04°	0.698 mrad
Stiffness in Pitch	150 N-m/°	116 µrad/N-m
Stiffness in Roll	150 N-m/°	116 µrad/N-m
Stiffness in Yaw	150 N-m/°	116 µrad/N-m
Power Supply	24-48 VDC	
Power Plug	2-pin Screw Terminal	
Maximum Current Draw	350 mA	

Specification	Value	Alternate Unit
Linear Motion Per Motor Rev	0.6096 mm	0.024"
Motor Steps Per Rev	200	
Motor Type	Stepper (2 phase)	
Motor Rated Current	600 mA/phase	
Inductance	3.5 mH/phase	
Default Resolution	1/64 of a step	
Mechanical Drive System	Precision lead screw	
Limit or Home Sensing	Magnetic hall sensor	
Manual Control	No	
Axes of Motion	1	
LED Indicators	Yes	
Mounting Interface	M3 and M6 threaded holes and M4 threaded centre hole	
Stage Parallelism	< 25 µm	< 0.000984"
Operating Temperature Range	0 to 50 °C	
RoHS Compliant	Yes	
CE Compliant	Yes	
Vacuum Compatible	No	
Weight	0.39 kg	0.860 lb



**Thrust Speed Performance** 



## **Thrust Speed Performance**







**Typical Accuracy** 





Typical Microstepping Accuracy

Typical Microstepping Accuracy



### LSM Linear Bearing Lifetime



### Contact

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