

## X-LSM150B-SE03 Datasheet



- 25, 50, 100, 150, 200 mm travel
- Up to 104 mm/s speed and up to 55 N thrust
- Recirculating ball bearing design for high load (25 kg) and long lifetime
- Built-in controller; daisy-chains with other Zaber products
- Integrated, 200 CPR, motor mounted encoder provides slip/stall detection and recovery
- Custom versions available

## X-LSM-E Series Overview

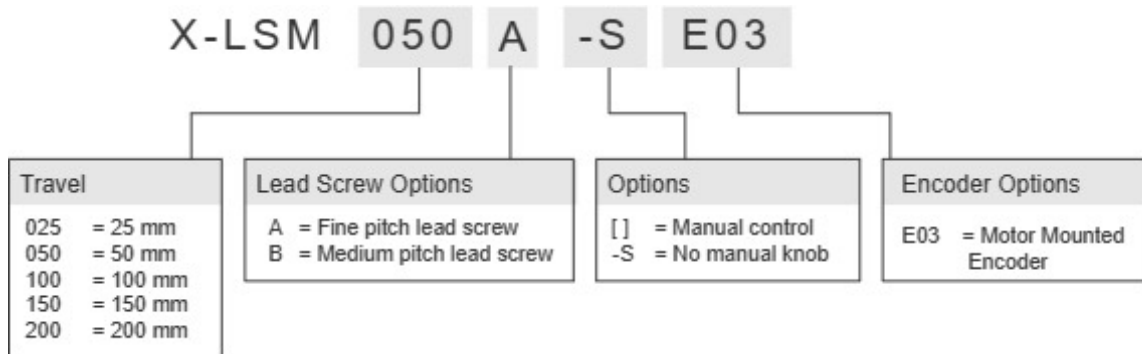
Zaber's X-LSM-E Series devices are computer-controlled, motorized linear stages with high thrust and speed capabilities and a compact size. They are stand-alone units requiring only a standard 24 V or 48 V power supply. The built-in motor encoder allows closed-loop operation and slip/stall recovery features. An optional indexed knob provides convenient manual control for versatile operation even without a computer.

These stages connect to the RS-232 port or USB port of any computer, and they can be daisy-chained with any other Zaber products. The daisy-chain also shares power, making it possible for multiple X-Series products to share a single power supply. Convenient locking, 4-pin, M8 connectors on the unit allow for secure connection between units.

At only 21 mm high, these miniature stages are excellent for applications where a small profile is required. The X-LSM-E's innovative design allows speeds up to 104 mm/s and loads up to 25 kg. Like all of Zaber's products, the X-LSM-E Series is designed to be 'plug and play' and very easy to set up and operate. If you are considering a multi-axis system, in the XY configuration, these stages make excellent microscope stages. Adding an X-JOY3 joystick controller allows manual control of both X and Y or XYZ axes from a single interface as well as allowing microscope stage positions to be saved and recalled at the touch of a button.

For more information visit: <https://www.zaber.com/products/linear-stages/X-LSM-E>

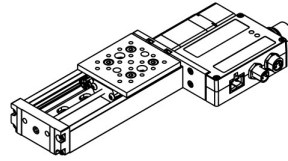
## X-LSM-E Series Part Numbering



# X-LSM150B-SE03 Drawings

# ZABER

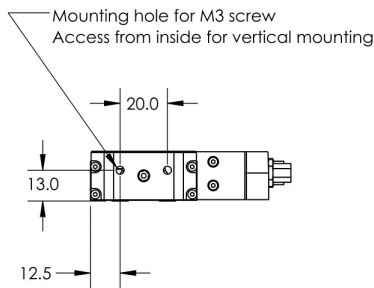
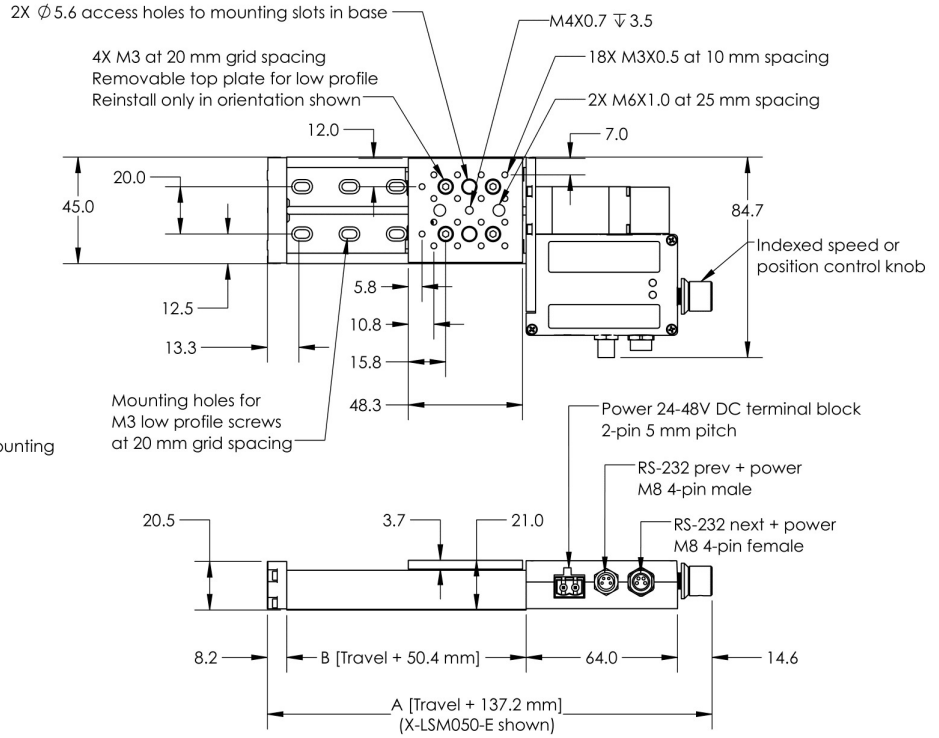
**X-LSM-E Miniature Motorized Linear Stage**  
 dimensions in mm



| Model Number* | Travel | A **  | B     |
|---------------|--------|-------|-------|
| X-LSM025      | 25.4   | 162.6 | 75.8  |
| X-LSM050      | 50.8   | 188.0 | 101.2 |
| X-LSM100      | 101.6  | 238.8 | 152.0 |
| X-LSM150      | 152.4  | 289.6 | 202.8 |
| X-LSM200      | 203.2  | 340.4 | 253.6 |

\*See product page for complete list of available models at [www.zaber.com](http://www.zaber.com)

\*\*Subtract 13.1 mm knob length from 'A' for -S versions without manual control



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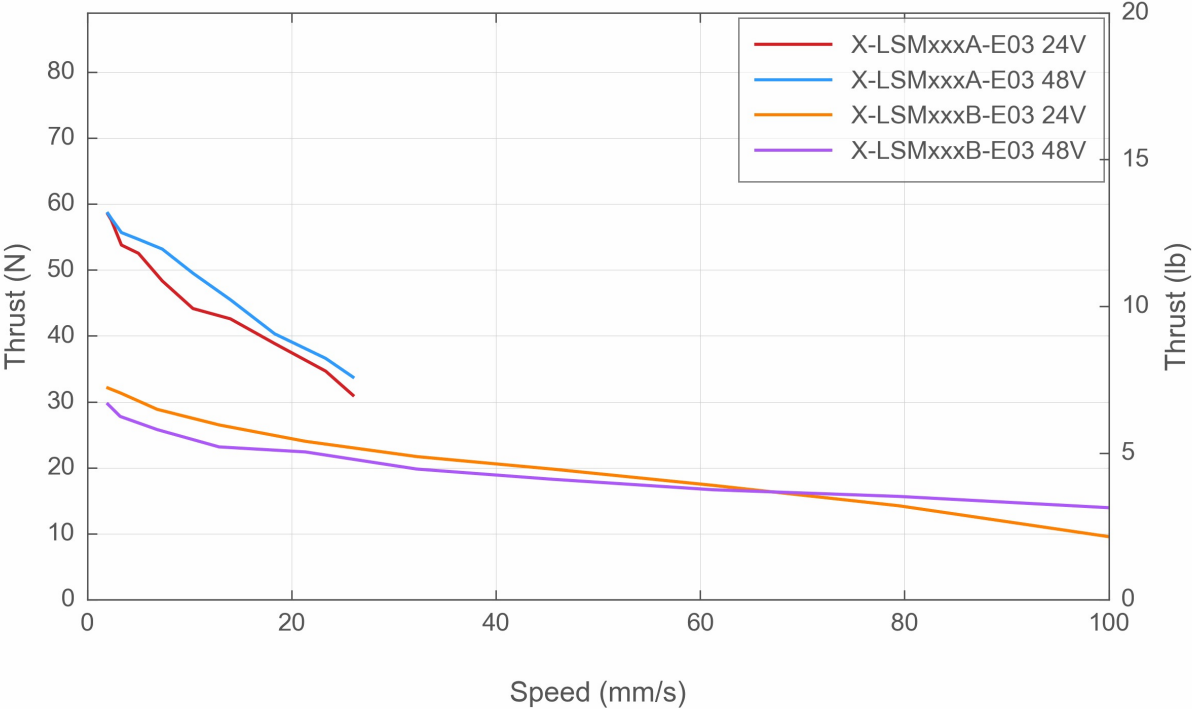
## X-LSM150B-SE03 Specifications

| Specification                       | Value                               | Alternate Unit          |
|-------------------------------------|-------------------------------------|-------------------------|
| Microstep Size (Default Resolution) | 0.1905 $\mu\text{m}$                |                         |
| Built-in Controller                 | Yes                                 |                         |
| Travel Range                        | 152.4 mm                            | 6.000"                  |
| Accuracy (unidirectional)           | 65 $\mu\text{m}$                    | 0.002559"               |
| Repeatability                       | < 6 $\mu\text{m}$                   | < 0.000236"             |
| Backlash                            | < 16 $\mu\text{m}$                  | < 0.000630"             |
| Maximum Speed                       | 104 mm/s                            | 4.094"/s                |
| Minimum Speed                       | 0.000116 mm/s                       | 0.000005"/s             |
| Speed Resolution                    | 0.000116 mm/s                       | 0.000005"/s             |
| Encoder Resolution                  | 200 CPR                             | 800 states/rev          |
| Encoder Type                        | Rotary quadrature encoder           |                         |
| Peak Thrust                         | 25 N                                | 5.6 lb                  |
| Maximum Continuous Thrust           | 25 N                                | 5.6 lb                  |
| Communication Interface             | RS-232                              |                         |
| Communication Protocol              | Zaber ASCII (Default), Zaber Binary |                         |
| Data Cable Connection               | Locking 4-pin M8                    |                         |
| Maximum Centered Load               | 250 N                               | 56.1 lb                 |
| Maximum Cantilever Load             | 10 N-m                              | 7.4 ft-lb               |
| Guide Type                          | Recirculating ball bearing          |                         |
| Vertical Runout                     | < 25 $\mu\text{m}$                  | < 0.000984"             |
| Horizontal Runout                   | < 23 $\mu\text{m}$                  | < 0.000906"             |
| Pitch                               | 0.04°                               | 0.698 mrad              |
| Roll                                | 0.05°                               | 0.873 mrad              |
| Yaw                                 | 0.05°                               | 0.873 mrad              |
| Stiffness in Pitch                  | 150 N-m/°                           | 116 $\mu\text{rad/N-m}$ |
| Stiffness in Roll                   | 150 N-m/°                           | 116 $\mu\text{rad/N-m}$ |
| Stiffness in Yaw                    | 150 N-m/°                           | 116 $\mu\text{rad/N-m}$ |
| Power Supply                        | 24-48 VDC                           |                         |
| Power Plug                          | 2-pin Screw Terminal                |                         |
| Maximum Current Draw                | 350 mA                              |                         |

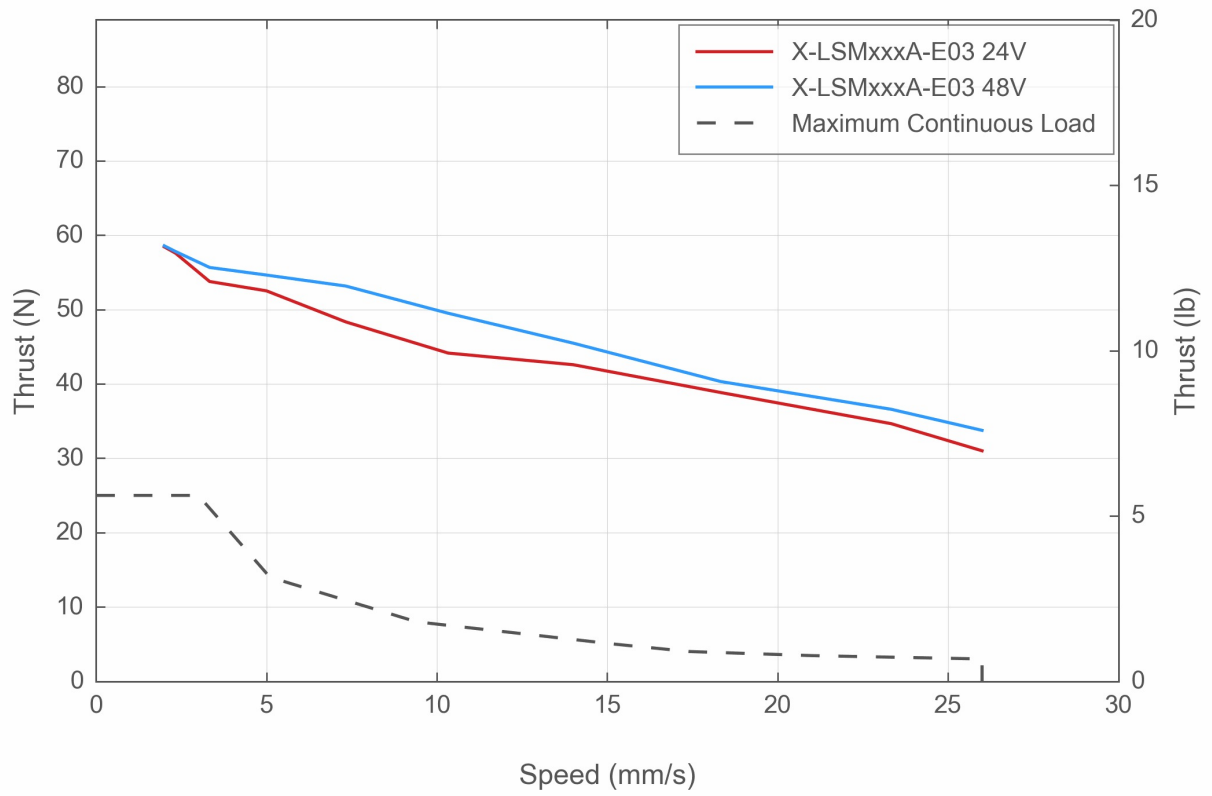
| Specification               | Value  | Alternate Unit |
|-----------------------------|--|----------------|
| Linear Motion Per Motor Rev | 2.4384 mm  | 0.096"         |
| Motor Steps Per Rev         | 200  |                |
| Motor Type                  | Stepper (2 phase)                                    |                |
| Motor Rated Current         | 600 mA/phase   |                |
| Inductance                  | 3.5 mH/phase   |                |
| Default Resolution          | 1/64 of a step                                       |                |
| Mechanical Drive System     | Precision lead screw                                 |                |
| Limit or Home Sensing       | Magnetic hall sensor                                 |                |
| Manual Control              | No   |                |
| Axes of Motion              | 1  |                |
| LED Indicators              | Yes  |                |
| Mounting Interface          | M3 and M6 threaded holes and M4 threaded centre hole |                |
| Stage Parallelism           | < 25 $\mu$ m   | < 0.000984"    |
| Operating Temperature Range | 0 to 50 °C   |                |
| RoHS Compliant              | Yes  |                |
| CE Compliant                | Yes  |                |
| Vacuum Compatible           | No   |                |
| Weight                      | 0.43 kg  | 0.948 lb       |

X-LSM-E Series Charts

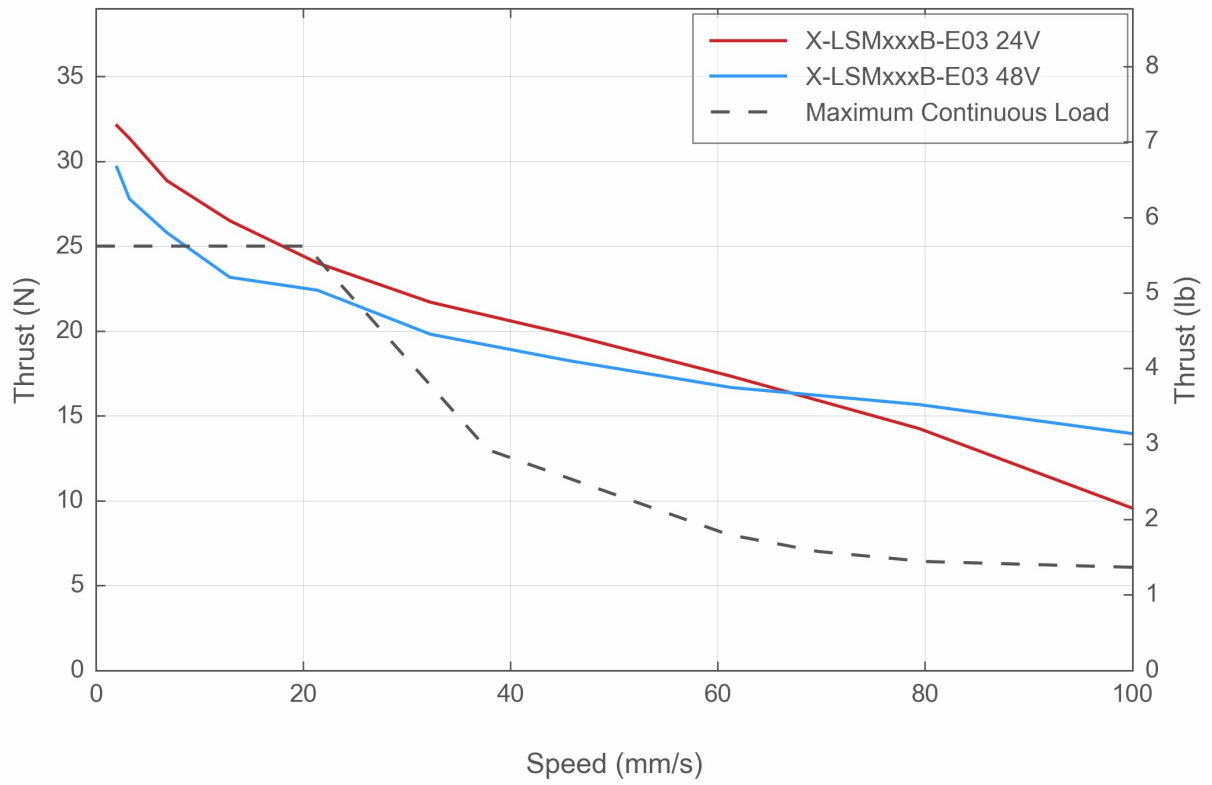
Thrust Speed Performance



## Thrust Speed Performance

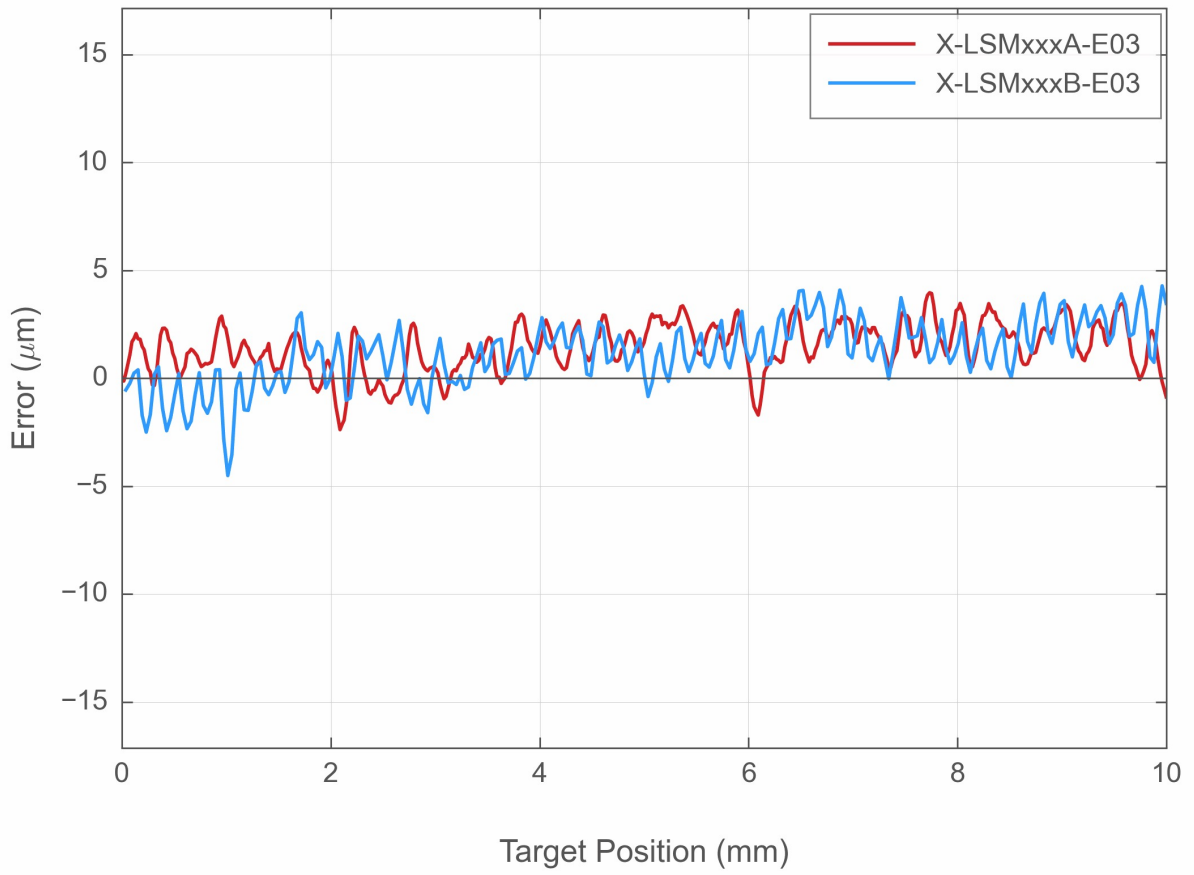


## Thrust Speed Performance

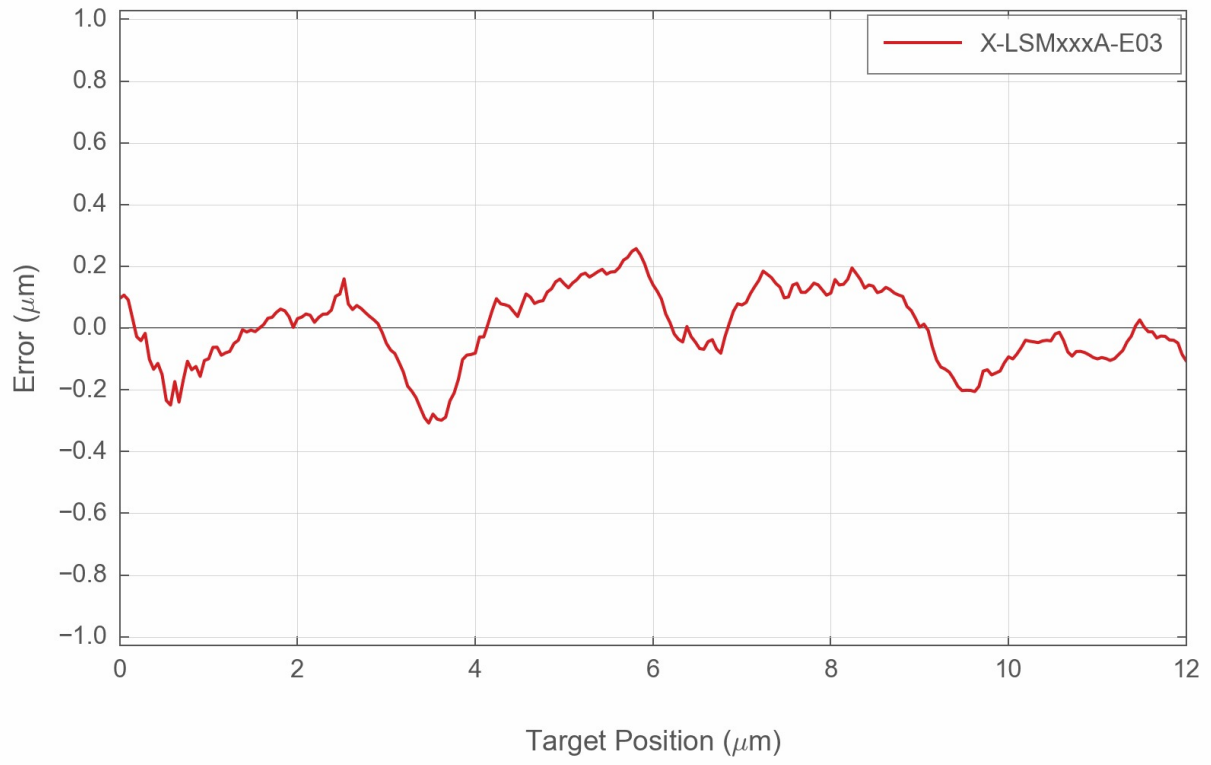




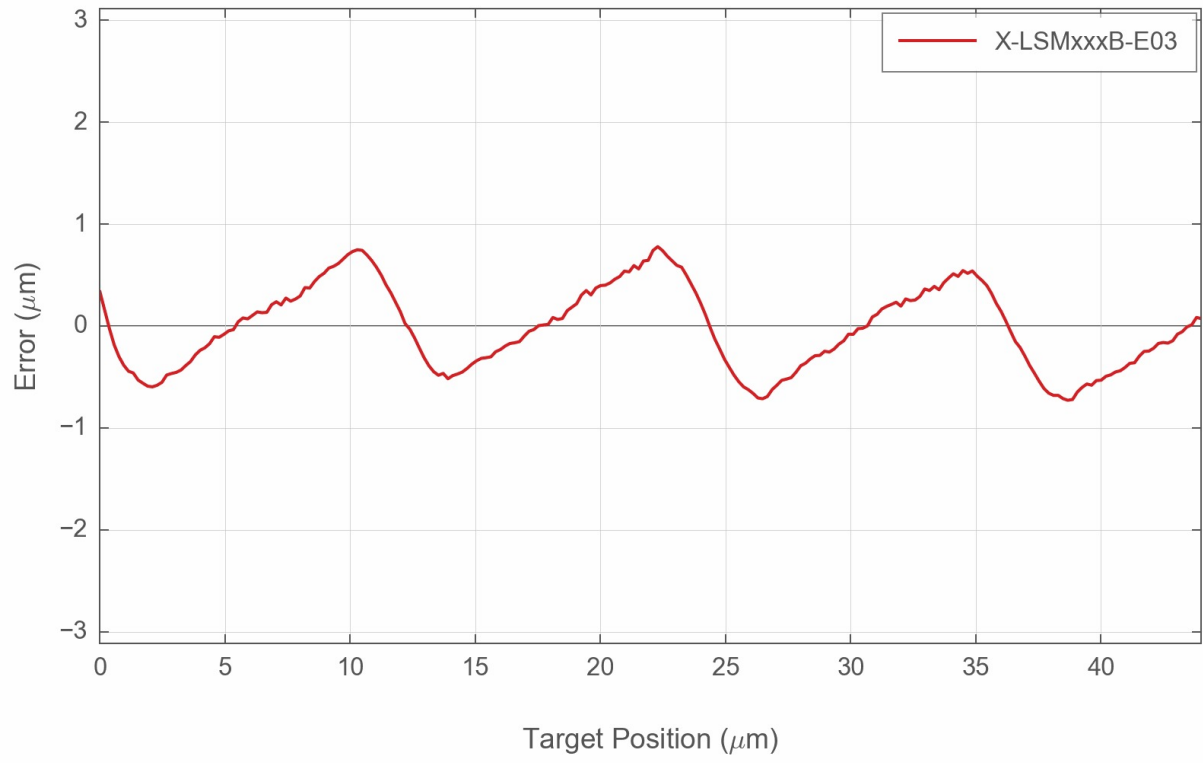
## Typical Accuracy



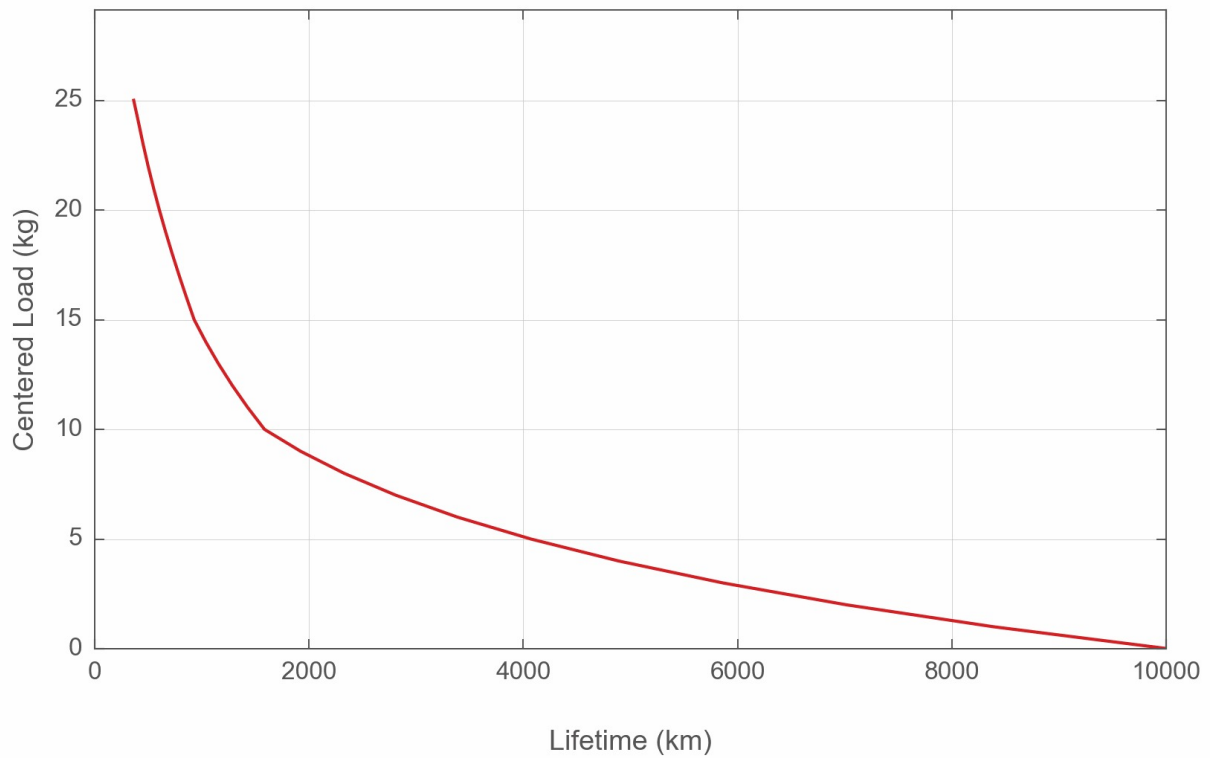
## Typical Microstepping Accuracy



## Typical Microstepping Accuracy



## LSM Linear Bearing Lifetime



### Contact

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